Name	Job Title	Area of Expertise
YAMAMOTO Ikuo	Professor	Robotics, System Engineering,
		Dynamics & Control

1. Main Research Topics

(1) Robotics

Offshore, Onshore, Aerospace, Medical robotics with autonomous function have been developed.

2 Offshore energy

Total technologies for practical renewable offshore energy system such as offshore wind have been developed.

③ Civil infrastructure

Robotic systems for assessing the degradation of civil and industrial infrastructure, including bridges, tunnels, roads, and plants have been developed.



2. Keywords

Robotics, Offshore energy, Infrastructure inspection robot

3. Remarks and Websites

2025 IEEE/IFAC GOLD BEST PAPER AWARD at the ICCAD'25 (Development of Land Robot), 2005 Archipelago award, France (Bio-Manoeuvring Type Underwater Vehicle), The world record of autonomous underwater vehicle cruising 317km by Urashima from Feb.26-28,2005.

MARIN CONTROL SYSTEMS, IFAC International Journal Robust and Nonlinear Control, Vol.11, No.13, 2001, Wiley.

Practical Robotics and Mechatronics, Marine, Space and Medical Applications, ISBN 978-4-320-08186-4, ISBN 978-4-320-08191-8, IET.

Red Tide Monitoring, Smart Fisheries, pp.136-137, Midori Shobo, ISBN 978-4-89531-885-3, 2023

researchmap: https://researchmap.jp/iyamamoto nu

Laboratory: https://robotics-mech-nagasaki-univ.conohawing.com/

Offshore Technology R&D Innovation Center HP: https://sites.google.com/view/otic-nagasaki-u